
dtcwt Documentation

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This library provides support for computing 1D, 2D and 3D dual-tree complex wavelet transforms and their inverse in Python along with some signal processing algorithms which make use of the DTCWT.

1.1 Getting Started

This section will guide you through using the `dtcwt` library. Once installed, you are most likely to use one of these functions:

- `dtcwt.dtwavexfm()` – 1D DT-CWT transform.
- `dtcwt.dtwaveifm()` – Inverse 1D DT-CWT transform.
- `dtcwt.dtwavexfm2()` – 2D DT-CWT transform.
- `dtcwt.dtwaveifm2()` – Inverse 2D DT-CWT transform.
- `dtcwt.dtwavexfm3()` – 3D DT-CWT transform.
- `dtcwt.dtwaveifm3()` – Inverse 3D DT-CWT transform.

See *API Reference* for full details on how to call these functions. We shall present some simple usage below.

1.1.1 Installation

The easiest way to install `dtcwt` is via `easy_install` or `pip`:

```
$ pip install dtcwt
```

If you want to check out the latest in-development version, look at [the project's GitHub page](#). Once checked out, installation is based on `setuptools` and follows the usual conventions for a Python project:

```
$ python setup.py install
```

(Although the `develop` command may be more useful if you intend to perform any significant modification to the library.) A test suite is provided so that you may verify the code works on your system:

```
$ python setup.py nosetests
```

This will also write test-coverage information to the `cover/` directory.

Building the documentation

There is a [pre-built](#) version of this documentation available online and you can build your own copy via the Sphinx documentation system:

```
$ python setup.py build_sphinx
```

Compiled documentation may be found in `build/docs/html/`.

1.2 Performing the DTCWT

1.2.1 1D transform

This example generates two 1D random walks and demonstrates reconstructing them using the forward and inverse 1D transforms. Note that `dtcwt.dtwavexfm()` and `dtcwt.dtwaveifm()` will transform columns of an input array independently:

```
import numpy as np
from matplotlib.pyplot import *

# Generate a 300x2 array of a random walk
vecs = np.cumsum(np.random.rand(300,2) - 0.5, 0)

# Show input
figure(1)
plot(vecs)
title('Input')

import dtcwt

# 1D transform
Yl, Yh = dtcwt.dtwavexfm(vecs)

# Inverse
vecs_recon = dtcwt.dtwaveifm(Yl, Yh)

# Show output
figure(2)
plot(vecs_recon)
title('Output')

# Show error
figure(3)
plot(vecs_recon - vecs)
title('Reconstruction error')

print('Maximum reconstruction error: {0}'.format(np.max(np.abs(vecs - vecs_recon))))

show()
```

1.2.2 2D transform

Using the pylab environment (part of matplotlib) we can perform a simple example where we transform the standard 'Lena' image and show the level 2 wavelet coefficients:

```
# Load the Lena image from the Internet into a StringIO object
from StringIO import StringIO
from urllib2 import urlopen
LENA_URL = 'http://www.ece.rice.edu/~wakin/images/lena512.pgm'
```

```

lena_file = StringIO(urlopen(LENA_URL).read())

# Parse the lena file and rescale to be in the range (0,1]
from scipy.misc import imread
lena = imread(lena_file) / 255.0

from matplotlib.pyplot import *
import numpy as np

# Show lena on the left
figure(1)
imshow(lena, cmap=cm.gray, clim=(0,1))

import dctwt

# Compute two levels of dctwt with the default wavelet family
Yh, Yl = dctwt.dtwavexfm2(lena, 2)

# Show the absolute images for each direction in level 2.
# Note that the 2nd level has index 1 since the 1st has index 0.
figure(2)
for slice_idx in xrange(Yl[1].shape[2]):
    subplot(2, 3, slice_idx)
    imshow(np.abs(Yl[1][:,:,slice_idx]), cmap=cm.spectral, clim=(0, 1))

# Show the phase images for each direction in level 2.
figure(3)
for slice_idx in xrange(Yl[1].shape[2]):
    subplot(2, 3, slice_idx)
    imshow(np.angle(Yl[1][:,:,slice_idx]), cmap=cm.hsv, clim=(-np.pi, np.pi))

show()

```

If the library is correctly installed and you also have matplotlib installed, you should see these three figures:

1.2.3 3D transform

In the examples below I assume you've imported pyplot and numpy and, of course, the `dctwt` library itself:

```

import numpy as np
from matplotlib.pyplot import *
from dctwt import *

```

We can demonstrate the 3D transform by generating a 64x64x64 array which contains the image of a sphere:

```

GRID_SIZE = 64
SPHERE_RAD = int(0.45 * GRID_SIZE) + 0.5

grid = np.arange(-(GRID_SIZE>>1), GRID_SIZE>>1)
X, Y, Z = np.meshgrid(grid, grid, grid)
r = np.sqrt(X*X + Y*Y + Z*Z)

sphere = 0.5 + 0.5 * np.clip(SPHERE_RAD-r, -1, 1)

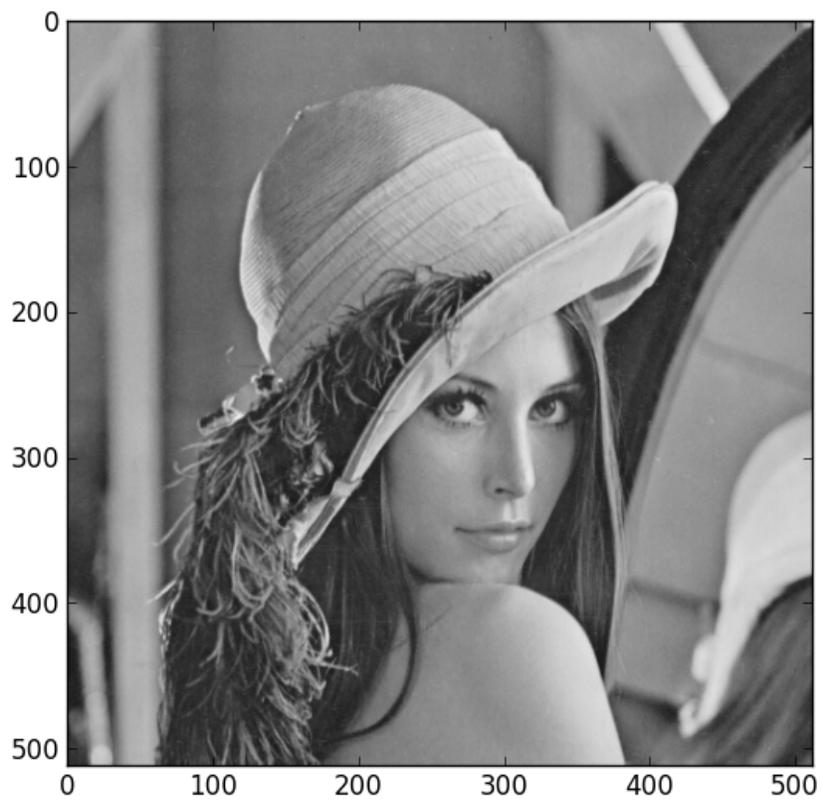
```

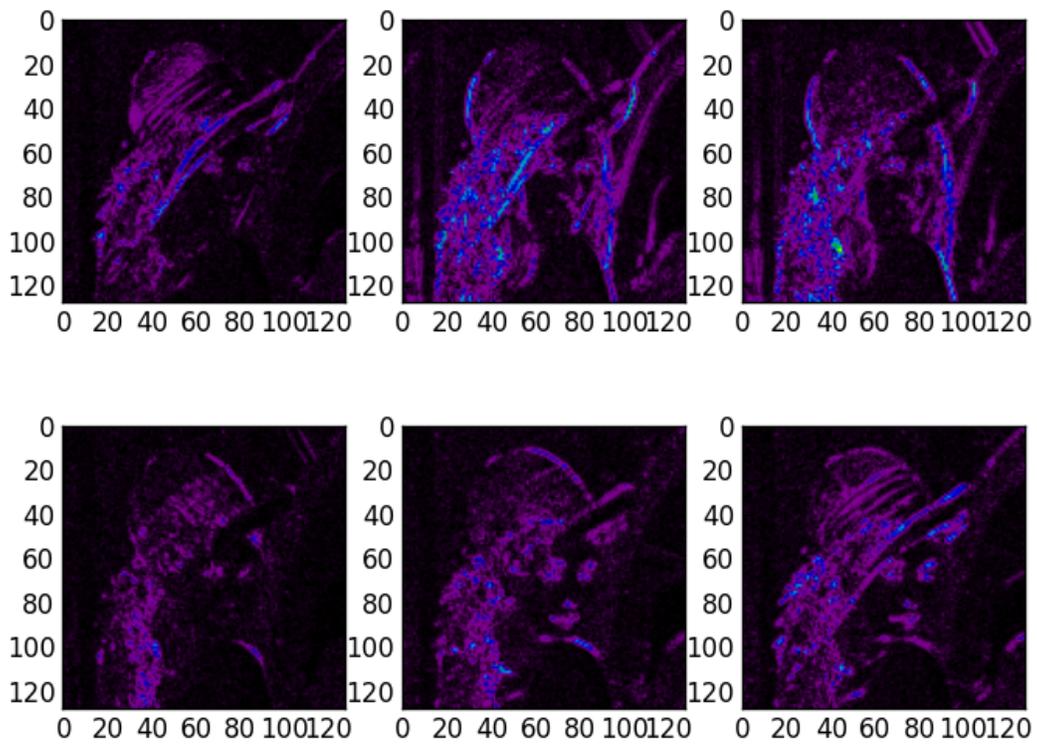
If we look at the central slice of this image, it looks like a circle:

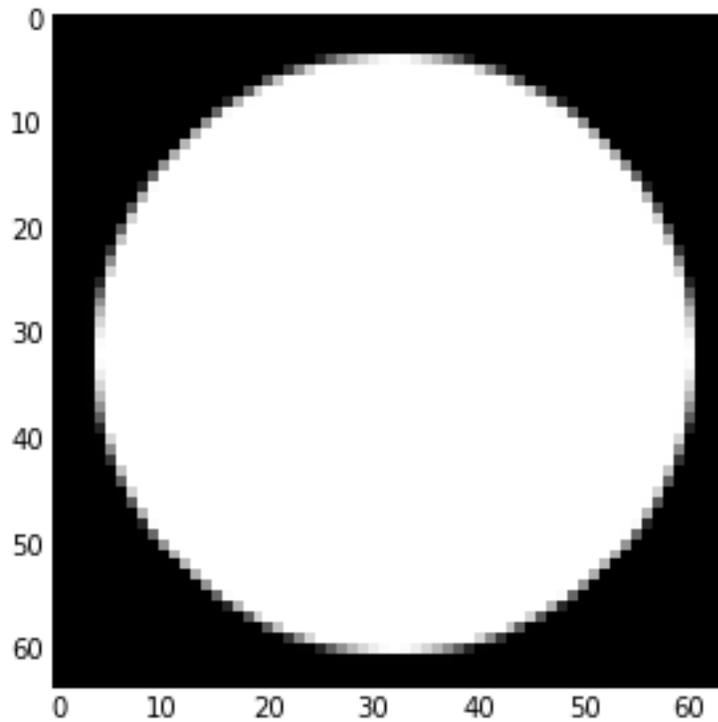
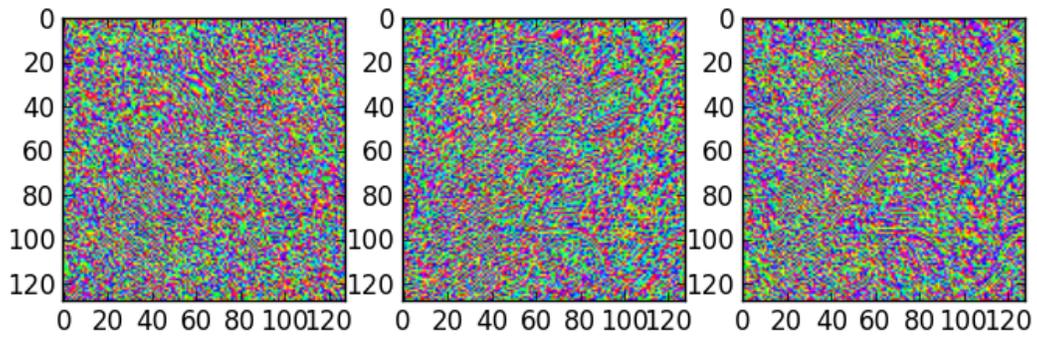
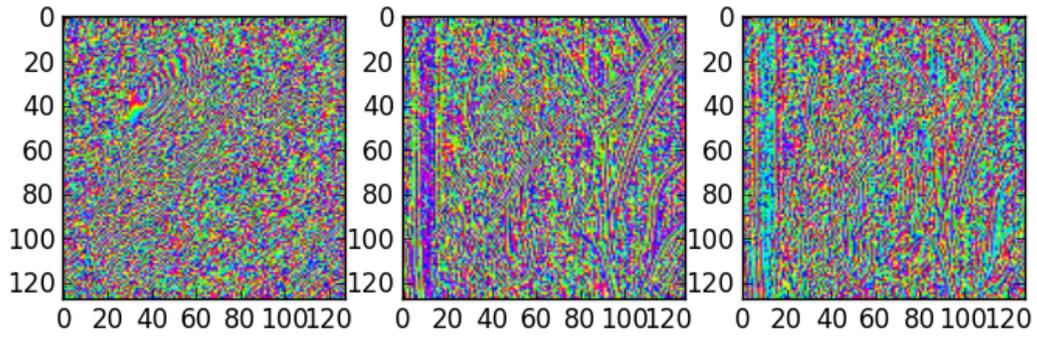
```

imshow(sphere[:, :, GRID_SIZE>>1], interpolation='none', cmap=cm.gray)

```







Performing the 3 level DT-CWT with the default wavelet selection is easy:

```
Yl, Yh = dtwavexfm3(sphere, 3)
```

The function returns the lowest level low pass image and a tuple of complex subband coefficients:

```
>>> print(Yl.shape)
(16, 16, 16)
>>> for subbands in Yh:
...     print(subbands.shape)
(32, 32, 32, 28)
(16, 16, 16, 28)
(8, 8, 8, 28)
```

Performing the inverse transform should result in perfect reconstruction:

```
>>> Z = dtwaveifm3(Yl, Yh)
>>> print(np.abs(Z - ellipsoid).max()) # Should be < 1e-12
8.881784197e-15
```

If you plot the locations of the large complex coefficients, you can see the directional sensitivity of the transform:

```
from mpl_toolkits.mplot3d import Axes3D

figure(figsize=(16,16))
nplts = Yh[-1].shape[3]
nrows = np.ceil(np.sqrt(nplts))
ncols = np.ceil(nplts / nrows)
W = np.max(Yh[-1].shape[:3])
for idx in xrange(Yh[-1].shape[3]):
    C = np.abs(Yh[-1][:,:, :, idx])
    ax = gcf().add_subplot(nrows, ncols, idx+1, projection='3d')
    ax.set_aspect('equal')
    good = C > 0.2*C.max()
    x,y,z = np.nonzero(good)
    ax.scatter(x, y, z, c=C[good].ravel())
    ax.auto_scale_xyz((0,W), (0,W), (0,W))

tight_layout()
```

For a further directional sensitivity example, see *Showing 3D Directional Sensitivity*.

1.2.4 Variant transforms

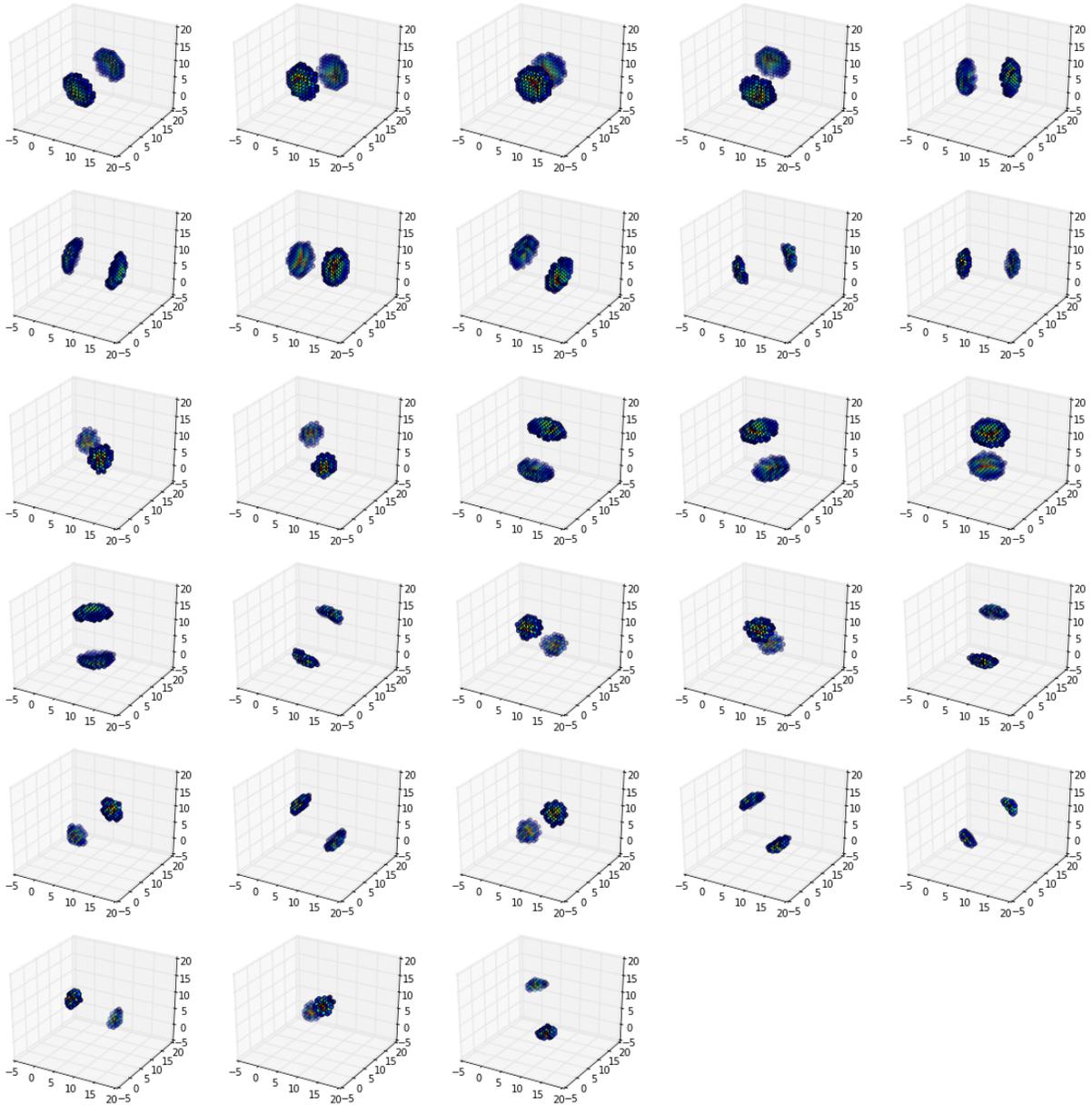
In addition to the basic 1, 2 and 3 dimensional DT-CWT, this library also supports a selection of variant transforms.

Rotational symmetry modified wavelet transform

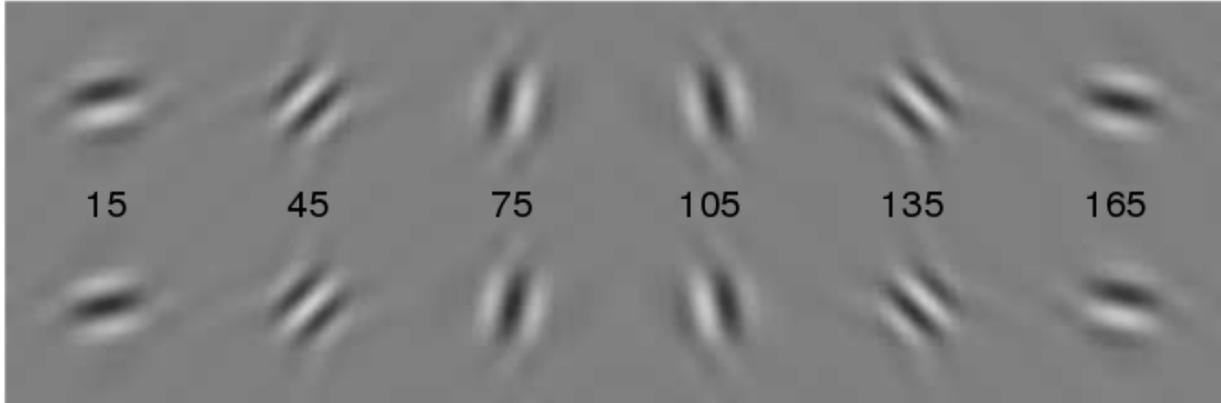
For some applications, one may prefer the subband responses to be more rotationally similar.

In the original 2-D DTCWT, the 45 and 135 degree subbands have passbands whose centre frequencies are somewhat further from the origin than those of the other four subbands. This results from the combination of two highpass 1-D wavelet filters to produce 2-D wavelets. The remaining subbands combine highpass and lowpass 1-D filters, and hence their centre frequencies are a factor of approximately $\sqrt{1.8}$ closer to the origin of the frequency plane.

The `dtwavexfm2b()` function employs an alternative bandpass 1-D filter in place of the highpass filter for the appropriate subbands. The image below illustrates the relevant differences in impulse and frequency responses[1].

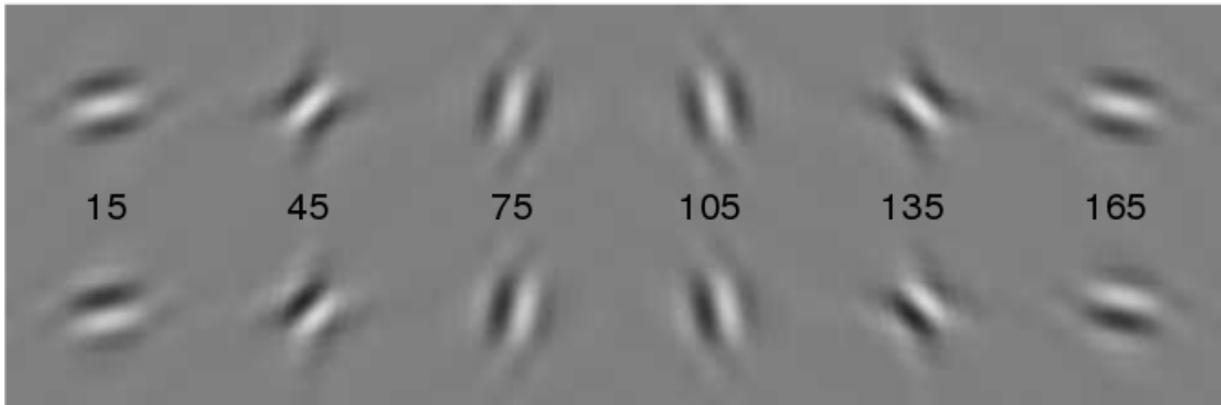


(a) Dual-Tree Complex Wavelets: Real Part



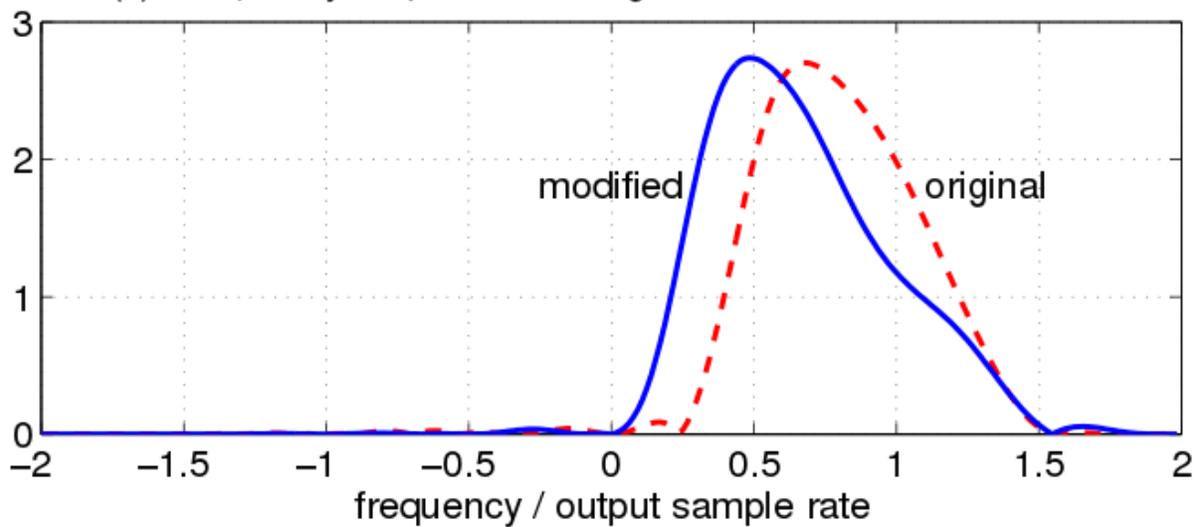
Imaginary Part

(b) Modified Complex Wavelets: Real Part



Imaginary Part

(c) Frequency responses of original and modified 1-D filters



Usage is very similar to the standard 2-D transform function, but the only supported parameters are 'near_sym_b_bp', 'qshift_b_bp'. These arguments are optional, but it is best practice to include them so that your intentions are clear (and because it is easier for others to spot than the difference between 2() and 2b()).

```
Yl, Yh = dtcwt.dtwavexfm2b(image, tfmlevel, 'near_sym_b_bp', 'qshift_b_bp')
```

While the Hilbert transform property of the DTCWT is preserved, perfect reconstruction is lost. However, in applications such as machine vision, where all subsequent operations on the image take place in the transform domain, this is of relatively minor importance.

For full details, refer to:

[1] N. G. Kingsbury. Rotation-invariant local feature matching with complex wavelets. *In Proc. European Conference on Signal Processing (EUSIPCO)*, pages 901–904, 2006. 2, 18, 21

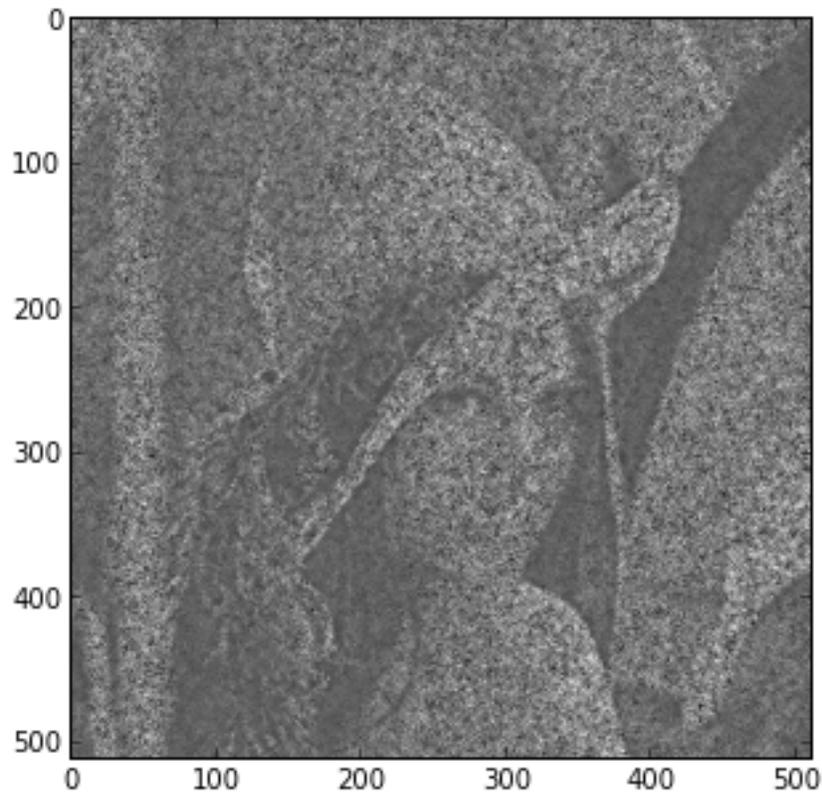
Example

Working on the Lena image, the standard 2-D DTCWT achieves perfect reconstruction:

```
# Perform the standard 2-D DTCWT
Yl, Yh = dtcwt.dtwavexfm2(image, tfmlevel, 'near_sym_b', 'qshift_b')

# Perform the inverse transform
Z = dtcwt.dtwaveifm2(Yl, Yh, biort='near_sym_b', qshift='qshift_b')

# Show the error
imshow(Z-image, cmap=cm.gray)
```



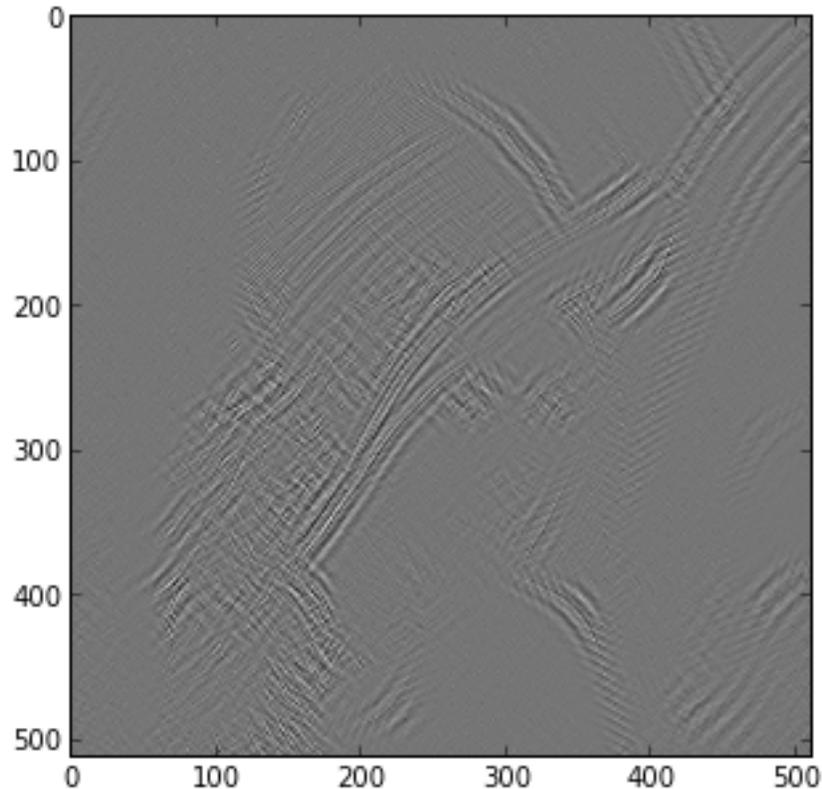
The error signal appears to be just noise, which we can attribute to floating-point precision.

Using the modified wavelets yields the following result:

```
# Perform the symmetry-modified 2-D DTCWT
Yl, Yh = dctwt.dtwavexfm2b(image, tfmlevel, 'near_sym_b_bp', 'qshift_b_bp')

# Perform the inverse transform
Z = dctwt.dtwaveifm2b(Yl, Yh, biort='near_sym_b_bp', qshift='qshift_b_bp')

# Show the error
imshow(Z-image, cmap=cm.gray)
```



As we would expect, the error is more significant, but only near 45 and 135 degree edge features.

1.3 Multiple Backend Support

The `dctwt` library currently provides two backends for computing the wavelet transform: a `NumPy` based implementation and an `OpenCL` implementation which uses the `PyOpenCL` bindings for Python.

1.3.1 NumPy

The `NumPy` backend is the reference implementation of the transform. All algorithms and transforms will have a `NumPy` backend. `NumPy` implementations are written to be efficient but also clear in their operation.

1.3.2 OpenCL

Some transforms and algorithms implement an OpenCL backend. This backend, if present, will provide an identical API to the NumPy backend. NumPy-based input may be passed in and out of the backends but if OpenCL-based input is passed in, a copy back to the host may be avoided in some cases. Not all transforms or algorithms have an OpenCL-based implementation and the implementation itself may not be full-featured.

OpenCL support depends on the `PyOpenCL` package being installed and an OpenCL implementation being installed on your machine. Attempting to use an OpenCL backend without both of these being present will result in a runtime (but not import-time) exception.

1.3.3 Which backend should I use?

The top-level transform routines, such as `dctwt.dtwavexfm2()`, will automatically use the NumPy backend. If you are not primarily focussed on speed, this is the correct choice since the NumPy backend has the fullest feature support, is the best tested and behaves correctly given single- and double-precision input.

If you care about speed and need only single-precision calculations, the OpenCL backend can provide significant speed-up. On the author's system, the 2D transform sees around a times 10 speed improvement.

1.3.4 Using a backend

The NumPy and OpenCL backends live in the `dctwt.backend.backend_numpy` and `dctwt.backend.backend_opengl` modules respectively. Both provide the same base API as defined in `dctwt.backend.base`.

Access to the 2D transform is via a `Transform2d` instance. For example, to compute the 2D DT-CWT of the 2D real array in `X`:

```
>>> from dctwt.backend.backend_numpy import Transform2d
>>> trans = Transform2d()           # You may optionally specify which wavelets to use here
>>> Y = trans.forward(X, nlevels=4) # Perform a 4-level transform of X
>>> imshow(Y.lowpass)              # Show coarsest scale low-pass image
>>> imshow(Y.subbands[-1][:,:,0])  # Show first coarsest scale subband
```

In this case `Y` is an instance of a class which behaves like `dctwt.backend.base.TransformDomainSignal`. Backends are free to return whatever result they like as long as the result can be used like this base class. (For example, the OpenCL backend returns a `dctwt.backend.backend_opengl.TransformDomainSignal` instance which keeps the device-side results available.)

1.4 DTCWT-based algorithms

1.4.1 Image Registration

The `dctwt.registration` module provides an implementation of a DTCWT-based image registration algorithm. The output is similar, but not identical, to “optical flow”. The underlying assumption is that the source image is a smooth locally-affine warping of a reference image. This assumption is valid in some classes of medical image registration and for video sequences with small motion between frames.

Algorithm overview

This section provides a brief overview of the algorithm itself. The algorithm is a 2D version of the 3D registration algorithm presented in [Efficient Registration of Nonrigid 3-D Bodies](#). The motion field between two images is a vector field whose elements represent the direction and distance of displacement for each pixel in the source image required to map it to a corresponding pixel in the reference image. In this algorithm the motion is described via the affine transform which can represent rotation, translation, shearing and scaling. An advantage of this model is that if the motion of two neighbouring pixels are from the same model then they will share affine transform parameters. This allows for large regions of the image to be considered as a whole and helps mitigate the aperture problem.

The model described below is based on the model in [Phase-based multidimensional volume registration](#) with changes designed to allow use of the DTCWT as a front end.

Motion constraint

The three-element homogeneous displacement vector at location \mathbf{x} is defined to be

$$\tilde{\mathbf{v}}(\mathbf{x}) \begin{bmatrix} \mathbf{v}(\mathbf{x}) \\ 1 \end{bmatrix}$$

where $\mathbf{v}(\mathbf{x})$ is the motion vector at location $\mathbf{x} = [x \ y]^T$. A motion constraint is a three-element vector, $\mathbf{c}(\mathbf{x})$ such that

$$\mathbf{c}^T(\mathbf{x}) \tilde{\mathbf{v}}(\mathbf{x}) = 0.$$

In the two-dimensional DTCWT, the phase of each complex highpass coefficient has an approximately linear relationship with the local shift vector. We can therefore write

$$\frac{\partial \theta_d}{\partial t} = \nabla_{\mathbf{x}} \theta_d \cdot \mathbf{v}(\mathbf{x})$$

where $\nabla_{\mathbf{x}} \theta_d [(\partial \theta_d / \partial x) \ (\partial \theta_d / \partial y)]^T$ and represents the phase gradient at \mathbf{x} for subband d in both of the x and y directions.

Numerical estimation of the partial derivatives of θ_d can be performed by noting that multiplication of a subband pixels's complex coefficient by the conjugate of its neighbour subtracts phase whereas multiplication by the neighbour adds phase. We can thus construct equivalents of forward-, backward- and central difference algorithms for phase gradients.

Comparing the relations above, it is clear that the motion constraint vector, $\mathbf{c}_d(\mathbf{x})$, corresponding to subband d at location \mathbf{x} satisfies the following:

$$\mathbf{c}_d(\mathbf{x}) = C_d(\mathbf{x}) \begin{bmatrix} \nabla_{\mathbf{x}} \theta_d \\ -\frac{\partial \theta_d}{\partial t} \end{bmatrix}$$

where $C_d(\mathbf{x})$ is some weighting factor which we can interpret as a measure of the confidence we have of subband d specifying the motion at \mathbf{x} .

This confidence measure can be heuristically designed. The measure used in this implementation is:

$$C_d(\mathbf{x}) = \frac{\left| \sum_{k=1}^4 u_k^* v_k \right|}{\sum_{k=1}^4 (|u_k|^3 + |v_k|^3) + \epsilon}.$$

where u_k and v_k are the wavelet coefficients in the reference and source transformed images, subscripts $k = 1 \dots 4$ denote the four diagonally neighbouring coefficients and ϵ is some small value to avoid division by zero when the wavelet coefficients are small. It is beyond the scope of this documentation to describe the design of this metric. Refer to the [original paper](#) for more details.

Cost function

The model is represented via the six parameters $a_1 \dots a_6$ such that

$$\mathbf{v}(\mathbf{x}) = \begin{bmatrix} 1 & 0 & x & 0 & y & 0 \\ 0 & 1 & 0 & x & 0 & y \end{bmatrix} \begin{bmatrix} a_1 \\ \vdots \\ a_6 \end{bmatrix} \mathbf{K}(\mathbf{x}) \mathbf{a}.$$

We then make the following definitions:

$$\tilde{\mathbf{K}}(\mathbf{x}) \begin{bmatrix} \mathbf{K}(\mathbf{x}) & \mathbf{0} \\ \mathbf{0} & 1 \end{bmatrix}, \quad \tilde{\mathbf{a}} \begin{bmatrix} \mathbf{a} \\ 1 \end{bmatrix}$$

and then the homogenous motion vector is given by

$$\tilde{\mathbf{v}}(\mathbf{x}) = \tilde{\mathbf{K}}(\mathbf{x}) \tilde{\mathbf{a}}.$$

Considering all size subband directions, we have:

$$\mathbf{c}_d(\mathbf{x}) \tilde{\mathbf{K}}(\mathbf{x}) \tilde{\mathbf{a}} = 0, \quad \forall d \in \{1, \dots, 6\}.$$

Each location \mathbf{x} has six constraint equations for six unknown affine parameters in $\tilde{\mathbf{a}}$. We can solve for $\tilde{\mathbf{a}}$ by minimising squared error $\epsilon(\mathbf{x})$:

$$\begin{aligned} \epsilon(\mathbf{x}) &= \sum_{d=1}^6 \left\| \mathbf{c}_d^T(\mathbf{x}) \tilde{\mathbf{K}}(\mathbf{x}) \tilde{\mathbf{a}} \right\|^2 \\ &= \sum_{d=1}^6 \tilde{\mathbf{a}}^T \tilde{\mathbf{K}}^T(\mathbf{x}) \mathbf{c}_d(\mathbf{x}) \mathbf{c}_d^T(\mathbf{x}) \tilde{\mathbf{K}}(\mathbf{x}) \tilde{\mathbf{a}} \\ &= \tilde{\mathbf{a}}^T \tilde{\mathbf{Q}}(\mathbf{x}) \tilde{\mathbf{a}} \end{aligned} \tag{1.1}$$

where

$$\tilde{\mathbf{Q}}(\mathbf{x}) = \sum_{d=1}^6 \tilde{\mathbf{K}}^T(\mathbf{x}) \mathbf{c}_d(\mathbf{x}) \mathbf{c}_d^T(\mathbf{x}) \tilde{\mathbf{K}}(\mathbf{x}).$$

In practice, in order to handle the registration of dissimilar image features and also to handle the aperture problem, it is helpful to combine $\tilde{\mathbf{Q}}(\mathbf{x})$ matrices across more than one level of DTCWT and over a slightly wider area within each level. This results in better estimates of the affine parameters and reduces the likelihood of obtaining singular matrices. We define locality χ to represent this wider spatial and inter-scale region, such that

$$\tilde{\mathbf{Q}}_\chi = \sum_{\mathbf{x} \in \chi} \tilde{\mathbf{Q}}(\mathbf{x}).$$

The $\tilde{\mathbf{Q}}_\chi$ matrices are symmetric and so can be written in the following form:

$$\tilde{\mathbf{Q}}_\chi = \begin{bmatrix} \mathbf{Q}_\chi & \mathbf{q}_\chi \\ \mathbf{q}_\chi^T & q_{0,\chi} \end{bmatrix}$$

where \mathbf{q}_χ is a six-element vector and $q_{0,\chi}$ is a scalar. Substituting into our squared error function gives

$$\epsilon_\chi = \mathbf{a}^T \mathbf{Q}_\chi \mathbf{a} + 2\mathbf{a}^T \mathbf{q}_\chi + q_{0,\chi}.$$

To minimize, we differentiate and set to zero. Hence,

$$\nabla_{\mathbf{a}} \epsilon_\chi = 2\mathbf{Q}_\chi \mathbf{a} + 2\mathbf{q}_\chi = 0$$

and so the local affine parameter vector satisfies

$$\mathbf{Q}_\chi \mathbf{a}_\chi = -\mathbf{q}_\chi.$$

In our implementation, we avoid calculating the inverse of \mathbf{Q}_χ directly and solve this equation by eigenvector decomposition.

Iteration

There are three steps in the full registration algorithm: transform the images to the DTCWT domain, perform motion estimation and register the source image. We do this via an iterative process where coarse-scale estimates of \mathbf{a}_χ are estimated from coarse-scale levels of the transform and progressively refined with finer-scale levels.

The following flow diagram, taken from the paper, illustrates the algorithm.

Using the implementation

The implementation of the image registration algorithm is accessed via the `dctwt.registration` module's functions. The two functions of most interest are `dctwt.registration.estimate_reg()` and `dctwt.registration.warp()`. The former will estimate \mathbf{a}_χ for each 8x8 block in the image and `dctwt.registration.warp()` will take these affine parameter vectors and warp an image with them.

Registration of a source image to a given reference image can be performed using two function calls not counting the DTCWT itself:

```
import dctwt.backend.backend_numpy as backend
import dctwt.registration as registration

# ... load two identically shaped NxM images into reference and source ...

# Transform reference and source
t = backend.Transform2d()
ref_t = t.forward(reference, nlevels=6)
src_t = t.forward(source, nlevels=6)

# Estimate registration from source -> reference
reg = registration.estimate_reg(src_t, ref_t)

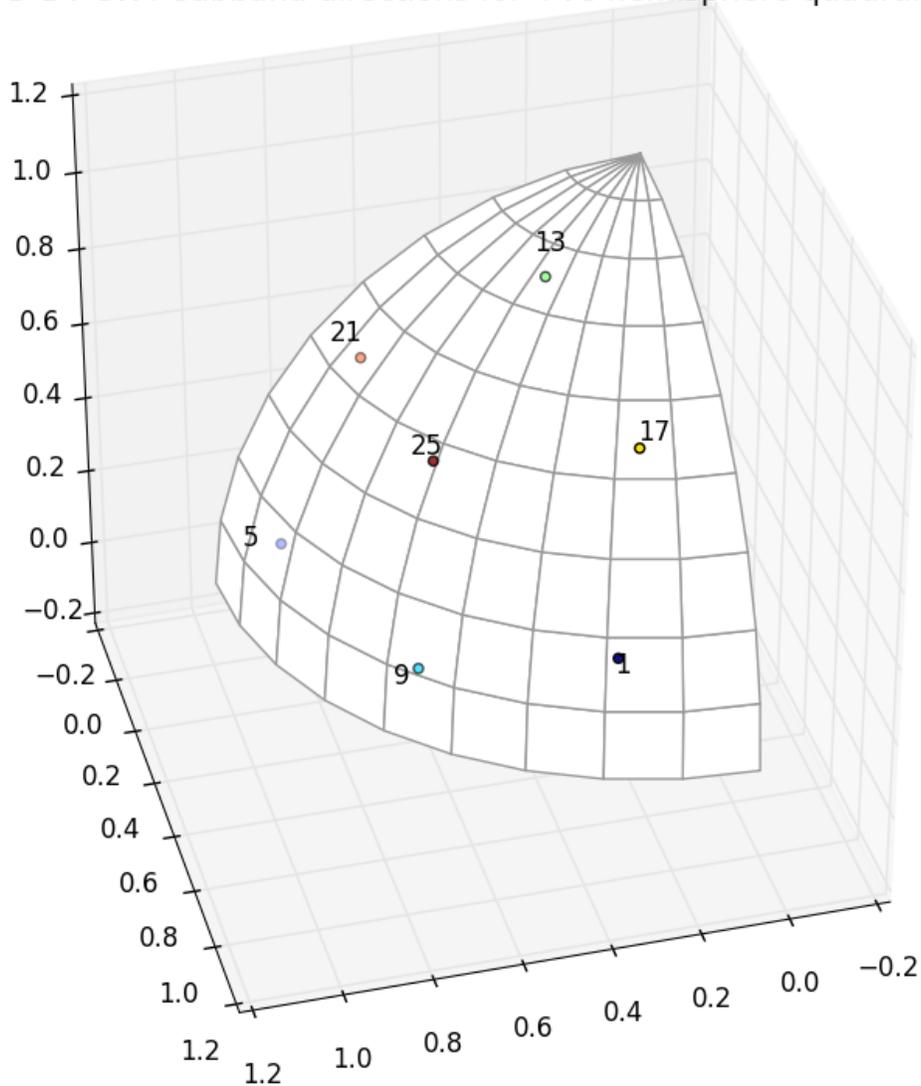
# Warp source image
registered_source = registration.warp(source, reg)
```

1.5 Example scripts

1.5.1 Showing 3D Directional Sensitivity

The `3d_dctwt_directionality.py` script in the `examples` directory shows how one may demonstrate the directional sensitivity of the 3D DT-CWT complex subband coefficients. It computes empirically the maximally sensitive directions for each subband and plots them in an interactive figure using `matplotlib`. A screenshot is reproduced below:

3D DT-CWT subband directions for +ve hemisphere quadrant



There are some points to note about this diagram. Each subband is labeled such that '1' refers to the first subband, '5' the fifth and so forth. On this diagram the subbands are all four apart reflecting the fact that, for example, subbands 2, 3 and 4 are positioned in the other four quadrants of the upper hemisphere reflecting the position of subband 1. There are seven visible subband directions in the +ve quadrant of the hemisphere and hence there are 28 directions in total over all four quadrants.

The source for the script is shown below:

```
#!/bin/python

"""
An example of the directional selectivity of 3D DT-CWT coefficients.

This example creates a 3D array holding an image of a sphere and performs the
3D DT-CWT transform on it. The locations of maxima (and their images about the
```

mid-point of the image) are determined for each complex coefficient at level 2. These maxima points are then shown on a single plot to demonstrate the directions in which the 3D DT-CWT transform is selective.

```

"""

# Import the libraries we need
from matplotlib.pyplot import *
import numpy as np
from mpl_toolkits.mplot3d import Axes3D
from mpl_toolkits.mplot3d.art3d import Poly3DCollection
from dctwt import dtwavexfm3, dtwaveifm3, biort, qshift

# Specify details about sphere and grid size
GRID_SIZE = 128
SPHERE_RAD = int(0.45 * GRID_SIZE) + 0.5

# Compute an image of the sphere
grid = np.arange(-(GRID_SIZE>>1), GRID_SIZE>>1)
X, Y, Z = np.meshgrid(grid, grid, grid)
r = np.sqrt(X*X + Y*Y + Z*Z)
sphere = (0.5 + np.clip(SPHERE_RAD-r, -0.5, 0.5)).astype(np.float32)

# Specify number of levels and wavelet family to use
nlevels = 2
b = biort('near_sym_a')
q = qshift('qshift_a')

# Form the DT-CWT of the sphere. We use discard_level_1 since we're
# uninterested in the inverse transform and this saves us some memory.
Yl, Yh = dtwavexfm3(sphere, nlevels, b, q, discard_level_1=True)

# Plot maxima
figure(figsize=(8,8))

ax = gcf().add_subplot(1,1,1, projection='3d')
ax.set_aspect('equal')
ax.view_init(35, 75)

# Plot unit sphere +ve octant
thetas = np.linspace(0, np.pi/2, 10)
phis = np.linspace(0, np.pi/2, 10)

def sphere_to_xyz(r, theta, phi):
    st, ct = np.sin(theta), np.cos(theta)
    sp, cp = np.sin(phi), np.cos(phi)
    return r * np.asarray((st*cp, st*sp, ct))

tris = []
rad = 0.99 # so that points plotted latter are not z-clipped
for t1, t2 in zip(thetas[:-1], thetas[1:]):
    for p1, p2 in zip(phis[:-1], phis[1:]):
        tris.append([
            sphere_to_xyz(rad, t1, p1),
            sphere_to_xyz(rad, t1, p2),
            sphere_to_xyz(rad, t2, p2),
            sphere_to_xyz(rad, t2, p1),
        ])

```

```
sphere = Poly3DCollection(tris, facecolor='w', edgecolor=(0.6,0.6,0.6))
ax.add_collection3d(sphere)

locs = []
scale = 1.1
for idx in xrange(Yh[-1].shape[3]):
    Z = Yh[-1][:,:, :, idx]
    C = np.abs(Z)
    max_loc = np.asarray(np.unravel_index(np.argmax(C), C.shape)) - np.asarray(C.shape)*0.5
    max_loc /= np.sqrt(np.sum(max_loc * max_loc))

    # Only record directions in the +ve octant (or those from the -ve quadrant
    # which can be flipped).
    if np.all(np.sign(max_loc) == 1):
        locs.append(max_loc)
        ax.text(max_loc[0] * scale, max_loc[1] * scale, max_loc[2] * scale, str(idx+1))
    elif np.all(np.sign(max_loc) == -1):
        locs.append(-max_loc)
        ax.text(-max_loc[0] * scale, -max_loc[1] * scale, -max_loc[2] * scale, str(idx+1))

# Plot all directions as a scatter plot
locs = np.asarray(locs)
ax.scatter(locs[:,0], locs[:,1], locs[:,2], c=np.arange(locs.shape[0]))

w = 1.1
ax.auto_scale_xyz([0, w], [0, w], [0, w])

legend()
title('3D DT-CWT subband directions for +ve hemisphere quadrant')
tight_layout()

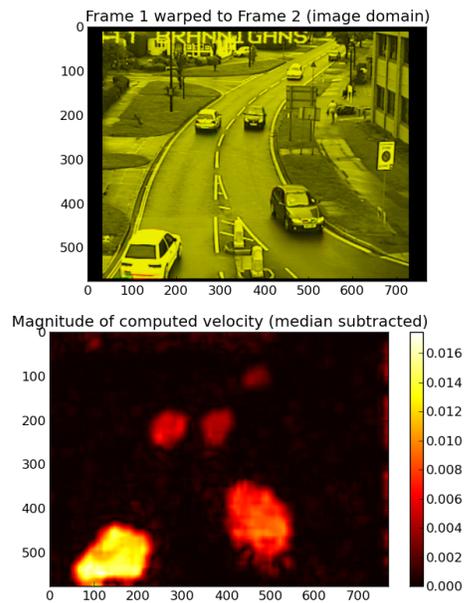
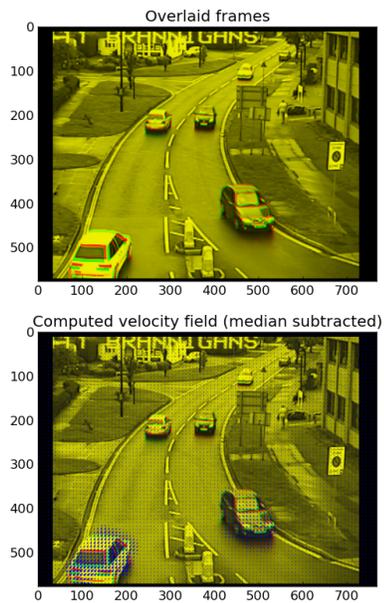
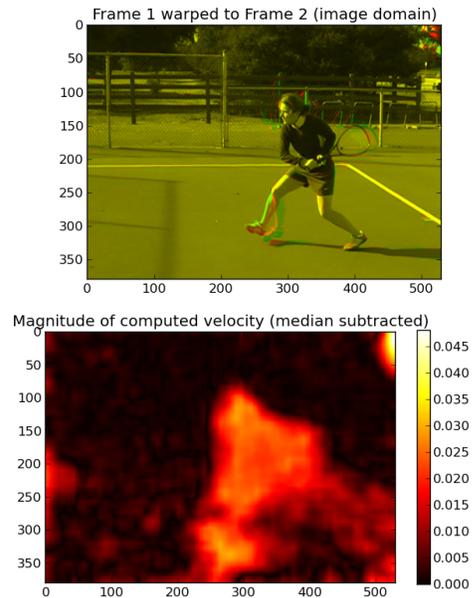
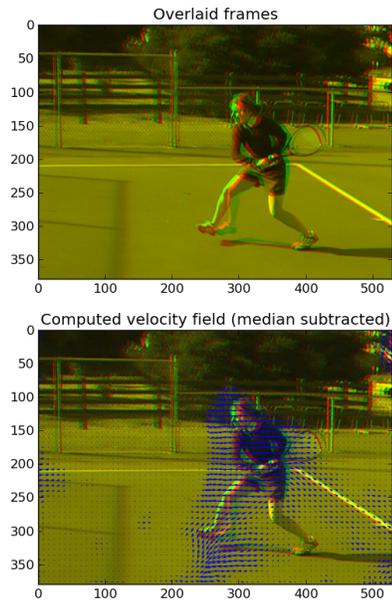
show()

# vim:sw=4:sts=4:et
```

1.5.2 2D Image Registration

This library includes support for 2D image registration modelled after the 3D algorithm outlined in the paper [Efficient Registration of Nonrigid 3-D Bodies](#). The `image-registration-2.py` script in the examples directory shows a complete worked example of using the registration API using two sets of source images: a woman playing tennis and some traffic at a road junction.

It will attempt to register two image pairs: a challenging sequence from a video sequence and a sequence from a traffic camera. The result is shown below.



1.6 API Reference

1.6.1 Computing the DT-CWT

These functions provide API-level compatibility with MATLAB.

Note: The functionality of `dtwavexfm2b` and `dtwaveifm2b` have been folded into `dtwavexfm2` and

`dtwaveifm2`. For convenience of porting MATLAB scripts, the original function names are available in the `dtcwt` module as aliases but they should not be used in new code.

`dtcwt.dtwavexfm` (X , $nlevels=3$, $biort='near_sym_a'$, $qshift='qshift_a'$, $include_scale=False$)

Perform a n -level DTCWT decomposition on a 1D column vector X (or on the columns of a matrix X).

Parameters

- **X** – 1D real array or 2D real array whose columns are to be transformed
- **nlevels** – Number of levels of wavelet decomposition
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.

Returns Yl The real lowpass image from the final level

Returns Yh A tuple containing the (N, M, 6) shape complex highpass subimages for each level.

Returns Yscale If `include_scale` is True, a tuple containing real lowpass coefficients for every scale.

If `biort` or `qshift` are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the `biort` case, this should be (h0o, g0o, h1o, g1o). In the `qshift` case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

Example:

```
# Performs a 5-level transform on the real image X using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Yl, Yh = dtwavexfm(X, 5, 'near_sym_b', 'qshift_b')
```

`dtcwt.dtwaveifm` (Yl , Yh , $biort='near_sym_a'$, $qshift='qshift_a'$, $gain_mask=None$)

Perform an n -level dual-tree complex wavelet (DTCWT) 1D reconstruction.

Parameters

- **Yl** – The real lowpass subband from the final level
- **Yh** – A sequence containing the complex highpass subband for each level.
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.
- **gain_mask** – Gain to be applied to each subband.

Returns Z Reconstructed real array.

The l -th element of `gain_mask` is gain for wavelet subband at level l . If `gain_mask[l] == 0`, no computation is performed for band l . Default `gain_mask` is all ones. Note that l is 0-indexed.

If `biort` or `qshift` are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the `biort` case, this should be (h0o, g0o, h1o, g1o). In the `qshift` case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

Example:

```
# Performs a reconstruction from Yl, Yh using the 13,19-tap filters
# for level 1 and the Q-shift 14-tap filters for levels >= 2.
Z = dtwaveifm(Yl, Yh, 'near_sym_b', 'qshift_b')
```

`dtcwt.dtwavexfm2` (X , $nlevels=3$, $biort='near_sym_a'$, $qshift='qshift_a'$, $include_scale=False$)

Perform a n -level DTCWT-2D decomposition on a 2D matrix X .

Parameters

- **X** – 2D real array
- **nlevels** – Number of levels of wavelet decomposition
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.

Returns Yl The real lowpass image from the final level

Returns Yh A tuple containing the complex highpass subimages for each level.

Returns Yscale If `include_scale` is True, a tuple containing real lowpass coefficients for every scale.

If `biort` or `qshift` are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the `biort` case, this should be (h0o, g0o, h1o, g1o). In the `qshift` case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

Example:

```
# Performs a 3-level transform on the real image X using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Yl, Yh = dtwavexfm2(X, 3, 'near_sym_b', 'qshift_b')
```

`dctwt.dtwaveifm2(Yl, Yh, biort='near_sym_a', qshift='qshift_a', gain_mask=None)`
Perform an n -level dual-tree complex wavelet (DTCWT) 2D reconstruction.

Parameters

- **Yl** – The real lowpass subband from the final level
- **Yh** – A sequence containing the complex highpass subband for each level.
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.
- **gain_mask** – Gain to be applied to each subband.

Returns Z Reconstructed real array

The (d, l) -th element of `gain_mask` is gain for subband with direction d at level l . If `gain_mask[d,l] == 0`, no computation is performed for band (d,l) . Default `gain_mask` is all ones. Note that both d and l are zero-indexed.

If `biort` or `qshift` are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the `biort` case, this should be (h0o, g0o, h1o, g1o). In the `qshift` case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

Example:

```
# Performs a 3-level reconstruction from Yl, Yh using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Z = dtwaveifm2(Yl, Yh, 'near_sym_b', 'qshift_b')
```

`dctwt.dtwavexfm2b(X, nlevels=3, biort='near_sym_a', qshift='qshift_a', include_scale=False)`
Perform a n -level DTCWT-2D decomposition on a 2D matrix X .

Parameters

- **X** – 2D real array
- **nlevels** – Number of levels of wavelet decomposition
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.

Returns Yl The real lowpass image from the final level

Returns Yh A tuple containing the complex highpass subimages for each level.

Returns Yscale If `include_scale` is True, a tuple containing real lowpass coefficients for every scale.

If `biort` or `qshift` are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the `biort` case, this should be (h0o, g0o, h1o, g1o). In the `qshift` case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

Example:

```
# Performs a 3-level transform on the real image X using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Yl, Yh = dtwavexfm2(X, 3, 'near_sym_b', 'qshift_b')
```

`dctwt.dtwaveifm2b`(Yl, Yh, biort='near_sym_a', qshift='qshift_a', gain_mask=None)

Perform an n -level dual-tree complex wavelet (DTCWT) 2D reconstruction.

Parameters

- **Yl** – The real lowpass subband from the final level
- **Yh** – A sequence containing the complex highpass subband for each level.
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.
- **gain_mask** – Gain to be applied to each subband.

Returns Z Reconstructed real array

The (d , l)-th element of `gain_mask` is gain for subband with direction d at level l . If `gain_mask[d,l] == 0`, no computation is performed for band (d,l). Default `gain_mask` is all ones. Note that both d and l are zero-indexed.

If `biort` or `qshift` are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the `biort` case, this should be (h0o, g0o, h1o, g1o). In the `qshift` case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

Example:

```
# Performs a 3-level reconstruction from Yl, Yh using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Z = dtwaveifm2(Yl, Yh, 'near_sym_b', 'qshift_b')
```

`dctwt.dtwavexfm3`(X, nlevels=3, biort='near_sym_a', qshift='qshift_a', ext_mode=4, discard_level_1=False)

Perform a n -level DTCWT-3D decomposition on a 3D matrix X .

Parameters

- **X** – 3D real array-like object
- **nlevels** – Number of levels of wavelet decomposition
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.
- **ext_mode** – Extension mode. See below.
- **discard_level_1** – True if level 1 high-pass bands are to be discarded.

Returns Yl The real lowpass image from the final level

Returns Yh A tuple containing the complex highpass subimages for each level.

Each element of Yh is a 4D complex array with the 4th dimension having size 28. The 3D slice $Yh[l][:, :, :, d]$ corresponds to the complex highpass coefficients for direction d at level l where d and l are both 0-indexed.

If *biort* or *qshift* are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the *biort* case, this should be (h0o, g0o, h1o, g1o). In the *qshift* case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

There are two values for *ext_mode*, either 4 or 8. If *ext_mode* = 4, check whether 1st level is divisible by 2 (if not we raise a `ValueError`). Also check whether from 2nd level onwards, the coefs can be divided by 4. If any dimension size is not a multiple of 4, append extra coefs by repeating the edges. If *ext_mode* = 8, check whether 1st level is divisible by 4 (if not we raise a `ValueError`). Also check whether from 2nd level onwards, the coeffs can be divided by 8. If any dimension size is not a multiple of 8, append extra coeffs by repeating the edges twice.

If *discard_level_1* is `True` the highpass coefficients at level 1 will be discarded. (And, in fact, will never be calculated.) This turns the transform from being 8:1 redundant to being 1:1 redundant at the cost of no-longer allowing perfect reconstruction. If this option is selected then $Yh[0]$ will be *None*. Note that `dtwaveifm3()` will accept $Yh[0]$ being *None* and will treat it as being zero.

Example:

```
# Performs a 3-level transform on the real 3D array X using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Yl, Yh = dtwavexfm3(X, 3, 'near_sym_b', 'qshift_b')
```

`dctwt.dtwaveifm3(Yl, Yh, biort='near_sym_a', qshift='qshift_a', ext_mode=4)`

Perform an n -level dual-tree complex wavelet (DTCWT) 3D reconstruction.

Parameters

- **Yl** – The real lowpass subband from the final level
- **Yh** – A sequence containing the complex highpass subband for each level.
- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.
- **ext_mode** – Extension mode. See below.

Returns Z Reconstructed real image matrix.

If *biort* or *qshift* are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the *biort* case, this should be (h0o, g0o, h1o, g1o). In the *qshift* case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

There are two values for *ext_mode*, either 4 or 8. If *ext_mode* = 4, check whether 1st level is divisible by 2 (if not we raise a `ValueError`). Also check whether from 2nd level onwards, the coefs can be divided by 4. If any dimension size is not a multiple of 4, append extra coefs by repeating the edges. If *ext_mode* = 8, check whether 1st level is divisible by 4 (if not we raise a `ValueError`). Also check whether from 2nd level onwards, the coeffs can be divided by 8. If any dimension size is not a multiple of 8, append extra coeffs by repeating the edges twice.

Example:

```
# Performs a 3-level reconstruction from Yl, Yh using the 13,19-tap
# filters for level 1 and the Q-shift 14-tap filters for levels >= 2.
Z = dtwaveifm3(Yl, Yh, 'near_sym_b', 'qshift_b')
```

`dctwt.biort(name)`

Load level 1 wavelet by name.

Parameters `name` – a string specifying the wavelet family name

Returns a tuple of vectors giving filter coefficients

Name	Wavelet
antonini	Antonini 9,7 tap filters.
legall	LeGall 5,3 tap filters.
near_sym_a	Near-Symmetric 5,7 tap filters.
near_sym_b	Near-Symmetric 13,19 tap filters.
near_sym_b_bp	Near-Symmetric 13,19 tap filters + BP filter

Return a tuple whose elements are a vector specifying the `h0o`, `g0o`, `h1o` and `g1o` coefficients.

See *Rotational symmetry modified wavelet transform* for an explanation of the `near_sym_b_bp` wavelet filters.

Raises

- **IOError** – if name does not correspond to a set of wavelets known to the library.
- **ValueError** – if name specifies a `qshift()` wavelet.

`dtcwt.qshift(name)`

Load level ≥ 2 wavelet by name,

Parameters `name` – a string specifying the wavelet family name

Returns a tuple of vectors giving filter coefficients

Name	Wavelet
qshift_06	Quarter Sample Shift Orthogonal (Q-Shift) 10,10 tap filters, (only 6,6 non-zero taps).
qshift_a	Q-shift 10,10 tap filters, (with 10,10 non-zero taps, unlike <code>qshift_06</code>).
qshift_b	Q-Shift 14,14 tap filters.
qshift_c	Q-Shift 16,16 tap filters.
qshift_d	Q-Shift 18,18 tap filters.
qshift_b_bp	Q-Shift 18,18 tap filters + BP

Return a tuple whose elements are a vector specifying the `h0a`, `h0b`, `g0a`, `g0b`, `h1a`, `h1b`, `g1a` and `g1b` coefficients.

See *Rotational symmetry modified wavelet transform* for an explanation of the `qshift_b_bp` wavelet filters.

Raises

- **IOError** – if name does not correspond to a set of wavelets known to the library.
- **ValueError** – if name specifies a `biort()` wavelet.

1.6.2 Backends

Base classes

class `dtcwt.backend.base.ReconstructedSignal(value)`

A representation of the reconstructed signal from the inverse transform. A backend is free to implement their own version of this class providing it corresponds to the interface documented.

value

A NumPy-compatible array containing the reconstructed signal.

class `dtcwt.backend.base.Transform2d(biort='near_sym_a', qshift='qshift_a')`

An implementation of a 2D DT-CWT transformation. Backends must provide a transform class which provides an interface compatible with this base class.

Parameters

- **biort** – Level 1 wavelets to use. See `biort()`.
- **qshift** – Level ≥ 2 wavelets to use. See `qshift()`.

If *biort* or *qshift* are strings, they are used as an argument to the `biort()` or `qshift()` functions. Otherwise, they are interpreted as tuples of vectors giving filter coefficients. In the *biort* case, this should be (h0o, g0o, h1o, g1o). In the *qshift* case, this should be (h0a, h0b, g0a, g0b, h1a, h1b, g1a, g1b).

In some cases the tuples may have more elements. This is used to represent the *Rotational symmetry modified wavelet transform*.

forward (*X*, *nlevels=3*, *include_scale=False*)

Perform a *n*-level DTCWT-2D decomposition on a 2D matrix *X*.

Parameters

- **X** – 2D real array
- **nlevels** – Number of levels of wavelet decomposition

Returns A `dtcwt.backend.TransformDomainSignal` compatible object representing the transform-domain signal

inverse (*td_signal*, *gain_mask=None*)

Perform an *n*-level dual-tree complex wavelet (DTCWT) 2D reconstruction.

Parameters

- **td_signal** – A `dtcwt.backend.TransformDomainSignal`-like class holding the transform domain representation to invert.
- **gain_mask** – Gain to be applied to each subband.

Returns A `dtcwt.backend.ReconstructedSignal` compatible instance with the reconstruction.

The (*d*, *l*)-th element of *gain_mask* is gain for subband with direction *d* at level *l*. If `gain_mask[d,l] == 0`, no computation is performed for band (*d*,*l*). Default *gain_mask* is all ones. Note that both *d* and *l* are zero-indexed.

class `dtcwt.backend.base.TransformDomainSignal` (*lowpass*, *subbands*, *scales=None*)

A representation of a transform domain signal.

Backends are free to implement any class which respects this interface for storing transform-domain signals. The inverse transform may accept a backend-specific version of this class but should always accept any class which corresponds to this interface.

lowpass

A NumPy-compatible array containing the coarsest scale lowpass signal.

subbands

A tuple where each element is the complex subband coefficients for corresponding scales finest to coarsest.

scales

(*optional*) A tuple where each element is a NumPy-compatible array containing the lowpass signal for corresponding scales finest to coarsest. This is not required for the inverse and may be *None*.

NumPy

A backend which uses NumPy to perform the filtering. This backend should always be available.

class `dtcwt.backend.backend_numpy.TransformDomainSignal` (*lowpass*, *subbands*,
scales=None)

A representation of a transform domain signal.

Backends are free to implement any class which respects this interface for storing transform-domain signals. The inverse transform may accept a backend-specific version of this class but should always accept any class which corresponds to this interface.

lowpass

A NumPy-compatible array containing the coarsest scale lowpass signal.

subbands

A tuple where each element is the complex subband coefficients for corresponding scales finest to coarsest.

scales

(*optional*) A tuple where each element is a NumPy-compatible array containing the lowpass signal for corresponding scales finest to coarsest. This is not required for the inverse and may be *None*.

class `dtcwt.backend.backend_numpy.Transform2d` (*biort='near_sym_a'*, *qshift='qshift_a'*)

An implementation of the 2D DT-CWT via NumPy. *biort* and *qshift* are the wavelets which parameterise the transform. Valid values are documented in `dtcwt.dtwavexfm2()`.

forward (*X*, *nlevels=3*, *include_scale=False*)

Perform a *n*-level DTCWT-2D decomposition on a 2D matrix *X*.

Parameters

- **X** – 2D real array
- **nlevels** – Number of levels of wavelet decomposition

Returns A `dtcwt.backend.TransformDomainSignal` compatible object representing the transform-domain signal

inverse (*td_signal*, *gain_mask=None*)

Perform an *n*-level dual-tree complex wavelet (DTCWT) 2D reconstruction.

Parameters

- **td_signal** – A `dtcwt.backend.TransformDomainSignal`-like class holding the transform domain representation to invert.
- **gain_mask** – Gain to be applied to each subband.

Returns A `dtcwt.backend.ReconstructedSignal` compatible instance with the reconstruction.

The (*d*, *l*)-th element of *gain_mask* is gain for subband with direction *d* at level *l*. If *gain_mask*[*d*,*l*] == 0, no computation is performed for band (*d*,*l*). Default *gain_mask* is all ones. Note that both *d* and *l* are zero-indexed.

OpenCL

Provide low-level OpenCL accelerated operations. This backend requires that PyOpenCL be installed.

class `dtcwt.backend.backend_opencl.TransformDomainSignal` (*lowpass*, *subbands*,
scales=None)

An interface-compatible version of `dtcwt.backend.TransformDomainSignal` where the initialiser arguments are assumed to be `pyopencl.array.Array` instances.

The attributes defined in `dtcwt.backend.TransformDomainSignal` are implemented via properties. The original OpenCL arrays may be accessed via the `cl_...` attributes.

Note: The copy from device to host is performed *once* and then memoized. This makes repeated access to the host-side attributes efficient but will mean that any changes to the device-side arrays will not be reflected in the host-side attributes after their first access. You should not be modifying the arrays once you return an instance of this class anyway but if you do, beware!

cl_lowpass

The CL array containing the lowpass image.

cl_subbands

A tuple of CL arrays containing the subband images.

cl_scales

(optional) Either None or a tuple of lowpass images for each scale.

class `dtcwt.backend.backend_opencl.Transform2d` (*biort*='near_sym_a', *qshift*='qshift_a',
queue=None)

An implementation of the 2D DT-CWT via OpenCL. *biort* and *qshift* are the wavelets which parameterise the transform. Valid values are documented in `dtcwt.dtwavexfm2()`.

If *queue* is non-None it is an instance of `pyopencl.CommandQueue` which is used to compile and execute the OpenCL kernels which implement the transform. If it is None, the first available compute device is used.

Note: At the moment *only* the **forward** transform is accelerated. The inverse transform uses the NumPy backend.

forward (*X*, *nlevels*=3, *include_scale*=False)

Perform a *n*-level DTCWT-2D decomposition on a 2D matrix *X*.

Parameters

- **X** – 2D real array
- **nlevels** – Number of levels of wavelet decomposition

Returns A `dtcwt.backend.TransformDomainSignal` compatible object representing the transform-domain signal

Note: *X* may be a `pyopencl.array.Array` instance which has already been copied to the device. In which case, it must be 2D. (I.e. a vector will not be auto-promoted.)

inverse (*td_signal*, *gain_mask*=None)

Perform an *n*-level dual-tree complex wavelet (DTCWT) 2D reconstruction.

Parameters

- **td_signal** – A `dtcwt.backend.TransformDomainSignal`-like class holding the transform domain representation to invert.
- **gain_mask** – Gain to be applied to each subband.

Returns A `dtcwt.backend.ReconstructedSignal` compatible instance with the reconstruction.

The (*d*, *l*)-th element of *gain_mask* is gain for subband with direction *d* at level *l*. If `gain_mask[d,l] == 0`, no computation is performed for band (*d*,*l*). Default *gain_mask* is all ones. Note that both *d* and *l* are zero-indexed.

1.6.3 Keypoint analysis

```
dctwt.keypoint.find_keypoints (highpass_subbands, method=None, alpha=1.0, beta=0.4,
                               kappa=0.16666666666666666, threshold=None,
                               max_points=None, upsample_keypoint_energy=None, up-
                               sample_subbands=None, refine_positions=True, skip_levels=1)
```

Parameters

- **highpass_subbands** – (NxMx6) matrix of highpass subband images
- **method** – (*optional*) string specifying which keypoint energy method to use
- **alpha** – (*optional*) scale parameter for 'fauqueur' method
- **beta** – (*optional*) shape parameter for 'fauqueur' method
- **kappa** – (*optional*) suppression parameter for 'kingsbury' method
- **threshold** – (*optional*) minimum keypoint energy of returned keypoints
- **max_points** – (*optional*) maximum number of keypoints to return
- **upsample_keypoint_energy** – is non-None, a string specifying a method used to upscale the keypoint energy map before finding keypoints
- **upsample_subbands** – is non-None, a string specifying a method used to upscale the subband image before finding keypoints
- **refine_positions** – (*optional*) should the keypoint positions be refined to sub-pixel accuracy
- **skip_levels** – (*optional*) number of levels of the transform to ignore before looking for keypoints

Returns (Px4) array of P keypoints in image co-ordinates

Warning: The interface and behaviour of this function is the subject of an open research project. It is provided in this release as a preview of forthcoming functionality but it is subject to change between releases.

The rows of the returned keypoint array give the x co-ordinate, y co-ordinate, scale and keypoint energy. The rows are sorted in order of decreasing keypoint energy.

If *refine_positions* is `True` then the positions (and energy) of the keypoints will be refined to sub-pixel accuracy by fitting a quadratic patch. If *refine_positions* is `False` then the keypoint locations will be those corresponding directly to pixel-wise maxima of the subband images.

The *max_points* and *threshold* parameters are cumulative: if both are specified then the *max_points* greatest energy keypoints with energy greater than *threshold* will be returned.

Usually the keypoint energies returned from the finest scale level are dominated by noise and so one usually wants to specify *skip_levels* to be 1 or 2. If *skip_levels* is 0 then all levels will be used to compute keypoint energy.

The *upsample_subbands* and *upsample_keypoint_energy* parameters are used to control whether the individual subband coefficients and/or the keypoint energy map are upsampled by 2 before finding keypoints. If these parameters are `None` then no corresponding upscaling is performed. If non-None they specify the upscale method as outlined in `dctwt.sampling.upsample()`.

If *method* is `None`, the default 'fauqueur' method is used.

Name	Description	Parameters used
fauqueur	Geometric mean of absolute values[1]	α, β
bendale	Minimum absolute value[2]	none
kingsbury	Cross-product of orthogonal subbands	κ

[1] Julien Fauqueur, Nick Kingsbury, and Ryan Anderson. *Multiscale Keypoint Detection using the Dual-Tree Complex Wavelet Transform*. 2006 International Conference on Image Processing, pages 1625-1628, October 2006. ISSN 1522-4880. doi: 10.1109/ICIP.2006.312656. <http://ieeexplore.ieee.org/lpdocs/epic03/wrapper.htm?arnumber=4106857>.

[2] Pashmina Bendale, Bill Triggs, and Nick Kingsbury. *Multiscale Keypoint Analysis based on Complex Wavelets*. In British Machine Vision Conference (BMVC), 2010. http://www-sigproc.eng.cam.ac.uk/~pb397/publications/BTK_BMVC_2010_abstract.pdf.

1.6.4 Image sampling

This module contains function for rescaling and re-sampling high- and low-pass subbands.

Note: All of these functions take an integer co-ordinate (x, y) to be the *centre* of the corresponding pixel. Therefore the upper-left pixel notionally covers the interval $(-0.5, 0.5)$ in x and y . An image with N rows and M columns, therefore, has an extent $(-0.5, M-0.5)$ on the x -axis and an extent of $(-0.5, N-0.5)$ on the y -axis. The rescale and upsample functions in this module will use this region as the extent of the image.

`dtcwt.sampling.sample` (*im*, *xs*, *ys*, *method=None*)

Sample image at (x,y) given by elements of *xs* and *ys*. Both *xs* and *ys* must have identical shape and output will have this same shape. The location (x,y) refers to the *centre* of `im[y, x]`. Samples at fractional locations are calculated using the method specified by *method* (or 'lanczos' if *method* is None.)

Parameters

- **im** – array to sample from
- **xs** – x co-ordinates to sample
- **ys** – y co-ordinates to sample
- **method** – one of 'bilinear', 'lanczos' or 'nearest'

Raises ValueError if *xs* and *ys* have differing shapes

`dtcwt.sampling.sample_highpass` (*im*, *xs*, *ys*, *method=None*)

As `sample()` except that the highpass image is first phase shifted to be centred on approximately DC.

`dtcwt.sampling.rescale` (*im*, *shape*, *method=None*)

Return a resampled version of *im* scaled to *shape*.

Since the centre of pixel (x,y) has co-ordinate (x,y) the extent of *im* is actually $x \in (-0.5, w - 0.5]$ and $y \in (-0.5, h - 0.5]$ where (y,x) is *im.shape*. This returns a sampled version of *im* that has the same extent as a *shape*-sized array.

`dtcwt.sampling.rescale_highpass` (*im*, *shape*, *method=None*)

As `rescale()` except that the highpass image is first phase shifted to be centred on approximately DC.

`dtcwt.sampling.upsample` (*image*, *method=None*)

Specialised function to upsample an image by a factor of two using a specified sampling method. If *image* is an array of shape $(N \times M \times \dots)$ then the output will have shape $(2N \times 2M \times \dots)$. Only rows and columns are upsampled, depth axes and greater are interpolated but are not upsampled.

Parameters

- **image** – an array containing the image to upsample
- **method** – if non-None, a string specifying the sampling method to use.

If *method* is None, the default sampling method 'lanczos' is used. The following sampling methods are supported:

Name	Description
nearest	Nearest-neighbour sampling
bilinear	Bilinear sampling
lanczos	Lanczos sampling with window radius of 3

`dtcwt.sampling.upsample_highpass(im, method=None)`

As `upsample()` except that the highpass image is first phase rolled so that the filter has approximate DC centre frequency. The upshot is that this is the function to use when re-sampling complex subband images.

1.6.5 Image registration

Note: This module is experimental. It's API may change between versions.

This module implements function for DTCWT-based image registration as outlined in [1]. These functions are 2D-only for the moment.

The functions in the top-level `dtcwt.registration` module are imported as a convenience from `dtcwt.numpybackend`. You could also import `dtcwt.numpybackend` directly to explicitly select backend.

`dtcwt.registration.estimateereg(reference, target)`

Estimate registration from reference image to target.

Parameters

- **reference** – transformed reference image
- **target** – transformed target image

The *reference* and *transform* parameters should support the same API as `dtcwt.backend.base.TransformDomainSignal`.

The local affine distortion is estimated at at 8x8 pixel scales. Return a NxMx6 array where the 6-element vector at (N,M) corresponds to the affine distortion parameters for the 8x8 block with index (N,M).

Use the `velocityfield()` function to convert the return value from this function into a velocity field.

`dtcwt.registration.velocityfield(avecs, shape, method=None)`

Given the affine distortion parameters returned from `estimateereg()`, return a tuple of 2D arrays giving the x- and y- components of the velocity field. The shape of the velocity component field is *shape*. The velocities are measured in terms of normalised units where the image has width and height of unity.

The *method* parameter is interpreted as in `dtcwt.sampling.rescale()` and is the sampling method used to resize *avecs* to *shape*.

`dtcwt.registration.warp(I, avecs, method=None)`

A convenience function to warp an image according to the velocity field implied by *avecs*.

`dtcwt.registration.warptransform(t, avecs, levels, method=None)`

Return a warped version of a transformed image acting only on specified levels.

Parameters

- **t** – a transformed image

- **avecs** – an array of affine distortion parameters
- **levels** – a sequence of 0-based indices specifying which levels to act on

t should be a `dtcwt.backend.base.TransformDomainSignal`-compatible instance.

The *method* parameter is interpreted as in `dtcwt.sampling.rescale()` and is the sampling method used to resize *avecs* to *shape*.

Note: This function will clone the transform *t* but it is a shallow clone where possible. Only the levels specified in *levels* will be deep-copied and warped.

1.6.6 Miscellaneous and low-level support functions

A normal user should not need to call these functions but they are documented here just in case you do. Useful utilities for testing the 2-D DTCWT with synthetic images

`dtcwt.utils.appropriate_complex_type_for(X)`

Return an appropriate complex data type depending on the type of X. If X is already complex, return that, if it is floating point return a complex type of the appropriate size and if it is integer, choose an complex floating point type depending on the result of `numpy.asfarray()`.

`dtcwt.utils.as_column_vector(v)`

Return *v* as a column vector with shape (N,1).

`dtcwt.utils.asfarray(X)`

Similar to `numpy.asfarray()` except that this function tries to preserve the original datatype of X if it is already a floating point type and will pass floating point arrays through directly without copying.

`dtcwt.utils.drawcirc(r, w, du, dv, N)`

Generate an image of size N*N pels, containing a circle radius *r* pels and centred at *du,dv* relative to the centre of the image. The edge of the circle is a cosine shaped edge of width *w* (from 10 to 90% points).

Python implementation by S. C. Forshaw, November 2013.

`dtcwt.utils.drawedge(theta, r, w, N)`

Generate an image of size N * N pels, of an edge going from 0 to 1 in height at *theta* degrees to the horizontal (top of image = 1 if angle = 0). *r* is a two-element vector, it is a coordinate in ij coords through which the step should pass. The shape of the intensity step is half a raised cosine *w* pels wide (*w*>=1).

T. E. Gale's enhancement to `drawedge()` for MATLAB, transliterated to Python by S. C. Forshaw, Nov. 2013.

`dtcwt.utils.reflect(x, minx, maxx)`

Reflect the values in matrix *x* about the scalar values *minx* and *maxx*. Hence a vector *x* containing a long linearly increasing series is converted into a waveform which ramps linearly up and down between *minx* and *maxx*. If *x* contains integers and *minx* and *maxx* are (integers + 0.5), the ramps will have repeated max and min samples.

`dtcwt.utils.stacked_2d_matrix_matrix_prod(mats1, mats2)`

Interpret *mats1* and *mats2* as arrays of 2D matrices. I.e. *mats1* has shape PxQxNxM and *mats2* has shape PxQxMxR. The result is a PxQxNxR array equivalent to:

```
result[i, j, :, :] = mats1[i, j, :, :].dot(mats2[i, j, :, :])
```

for all valid row and column indices *i* and *j*.

`dtcwt.utils.stacked_2d_matrix_vector_prod(mats, vecs)`

Interpret *mats* and *vecs* as arrays of 2D matrices and vectors. I.e. *mats* has shape PxQxNxM and *vecs* has shape PxQxM. The result is a PxQxN array equivalent to:

```
result[i, j, :] = mats[i, j, :, :].dot(vecs[i, j, :])
```

for all valid row and column indices i and j .

`dtcwt.utils.stacked_2d_vector_matrix_prod`(*vecs*, *mats*)

Interpret *mats* and *vecs* as arrays of 2D matrices and vectors. I.e. *mats* has shape $P \times Q \times N \times M$ and *vecs* has shape $P \times Q \times N$. The result is a $P \times Q \times M$ array equivalent to:

```
result[i, j, :] = mats[i, j, :, :].T.dot(vecs[i, j, :])
```

for all valid row and column indices i and j .

`dtcwt.lowlevel.coldfilt`(*X*, *ha*, *hb*)

Filter the columns of image *X* using the two filters *ha* and *hb* = `reverse(ha)`. *ha* operates on the odd samples of *X* and *hb* on the even samples. Both filters should be even length, and *h* should be approx linear phase with a quarter sample advance from its mid pt (i.e. $|h(m/2)| > |h(m/2 + 1)|$).

```

                ext          top edge                      bottom edge          ext
Level 1:      !            |                               |                               !
odd filt on .  b  b  b  b  a  a  a  a  a  a  a  a  a  a  b  b  b  b
odd filt on .      a  a  a  a  b  b  b  b  b  b  b  b  b  b  a  a  a  a
Level 2:      !            |                               |                               !
+q filt on x   b          b          a          a          a          a          b          b
-q filt on o       a          a          b          b          b          b          b          a          a

```

The output is decimated by two from the input sample rate and the results from the two filters, *Ya* and *Yb*, are interleaved to give *Y*. Symmetric extension with repeated end samples is used on the composite *X* columns before each filter is applied.

Raises `ValueError` if the number of rows in *X* is not a multiple of 4, the length of *ha* does not match *hb* or the lengths of *ha* or *hb* are non-even.

`dtcwt.lowlevel.colfilter`(*X*, *h*)

Filter the columns of image *X* using filter vector *h*, without decimation. If `len(h)` is odd, each output sample is aligned with each input sample and *Y* is the same size as *X*. If `len(h)` is even, each output sample is aligned with the mid point of each pair of input samples, and `Y.shape = X.shape + [1 0]`.

Parameters

- **X** – an image whose columns are to be filtered
- **h** – the filter coefficients.

Returns Y the filtered image.

`dtcwt.lowlevel.colifilt`(*X*, *ha*, *hb*)

Filter the columns of image *X* using the two filters *ha* and *hb* = `reverse(ha)`. *ha* operates on the odd samples of *X* and *hb* on the even samples. Both filters should be even length, and *h* should be approx linear phase with a quarter sample advance from its mid pt (i.e. $|h(m/2)| > |h(m/2 + 1)|$).

```

                ext          left edge                      right edge          ext
Level 2:      !            |                               |                               !
+q filt on x   b          b          a          a          a          a          b          b
-q filt on o       a          a          b          b          b          b          b          a          a
Level 1:      !            |                               |                               !
odd filt on .  b  b  b  b  a  a  a  a  a  a  a  a  a  a  b  b  b  b
odd filt on .      a  a  a  a  b  b  b  b  b  b  b  b  b  b  a  a  a  a

```

The output is interpolated by two from the input sample rate and the results from the two filters, *Ya* and *Yb*, are interleaved to give *Y*. Symmetric extension with repeated end samples is used on the composite *X* columns before each filter is applied.

Features of note

The features of the `dtcwt` library are:

- 1D, 2D and 3D forward and inverse Dual-tree Complex Wavelet Transform implementations.
- API similarity with the DTCWT MATLAB toolbox.
- Automatic selection of single versus double precision calculation.
- Built-in support for the most common complex wavelet families.

Licence

The original toolbox is copyrighted and there are some restrictions on use which are outlined in the file `ORIGINAL_README.txt`. Aside from portions directly derived from the original MATLAB toolbox, any additions in this library and this documentation are licensed under the 2-clause BSD licence as documented in the file `COPYING.txt`.

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